



#### FILTERLESS 3W CLASS-D STEREO AUDIO AMPLIFIER

## **Description**

The PAM8403 is a 3W, class-D audio amplifier. It offers low THD+N, allowing it to achieve high-quality sound reproduction. The new filterless architecture allows the device to drive the speaker directly, requiring no low-pass output filters, thus saving system cost and PCB area.

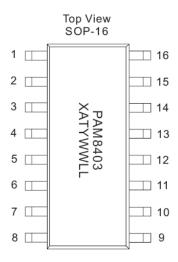
With the same numbers of external components, the efficiency of the PAM8403 is much better than that of Class-AB cousins. It can extend the battery life, which makes it well-suited for portable applications.

The PAM8403 is available in SOP-16 package.

#### **Features**

- 3W Output at 10% THD with a 4Ω Load and 5V Power Supply
- Filterless, Low Quiescent Current and Low EMI
- Low THD+N
- Superior Low Noise
- Efficiency up to 90%
- Short Circuit Protection
- Thermal Shutdown
- Few External Components to Save the Space and Cost
- Pb-Free Package

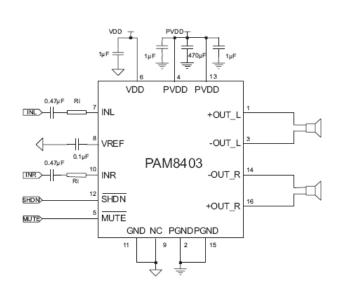
## **Pin Assignments**

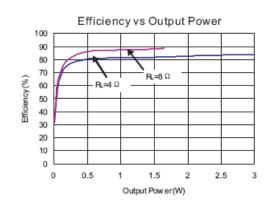


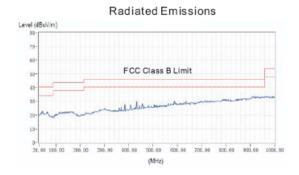
## **Applications**

- LCD Monitors / TV Projectors
- Notebook Computers
- Portable Speakers
- Portable DVD Players, Game Machines
- Cellular Phones/Speaker Phones

## **Typical Applications Circuit**





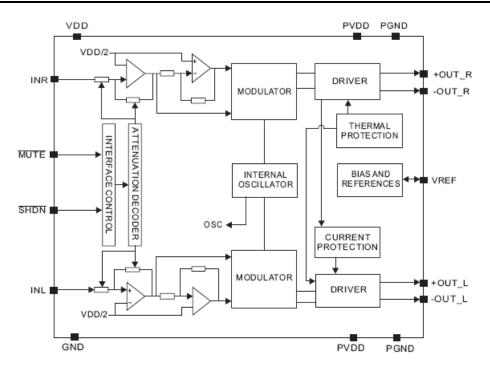




## **Pin Descriptions**

| Pin<br>Number | Pin<br>Name | Function  |
|---------------|-------------|---|
| 1             | +OUT_L      | Left Channel Positive Output  |
| 2             | PGND        | Power GND   |
| 3             | -OUT_L      | Left Channel Negative Output  |
| 4             | PVDD        | Power VDD   |
| 5             | MUTE        | Mute Control Input (active low)   |
| 6             | VDD         | Analog VDD  |
| 7             | INL         | Left Channel Input  |
| 8             | VREF        | Internal analog reference, connect a bypass capacitor from VREF to GND. |
| 9             | NC          | No Connact  |
| 10            | INR         | Right Channel Input   |
| 11            | GND         | Analog GND  |
| 12            | SHND        | Shutdown Control Input (active low)                                     |
| 13            | PVDD        | Power VDD   |
| 14            | -OUT_R      | Right Channel Negative Output   |
| 15            | PGND        | Power GND   |
| 16            | +OUT_R      | Right Channel Positive Output   |

## **Functional Block Diagram**







## Absolute Maximum Ratings (@TA = +25°C, unless otherwise specified.)

These are stress ratings only and functional operation is not implied. Exposure to absolute maximum ratings for prolonged time periods may affect device reliability. All voltages are with respect to ground.

| Parameter                      | Rating                        | Unit |
|--------------------------------|-------------------------------|------|
| Supply Voltage                 | 6.0                           | V    |
| Input Voltage                  | -0.3 to V <sub>DD</sub> +0.3V | V    |
| Operation Temperature Range    | -40 to +85                    |      |
| Maximum Junction Temperature   | 150                           |      |
| Operation Junction Temperature | -40 to +125                   | °C   |
| Storage Temperature            | -65 to +150                   |      |
| Soldering Temperature          | 300, 5 sec                    |      |

## Recommended Operating Conditions (@TA = +25°C, unless otherwise specified.)

| Parameter                   | Rating      | Unit |
|-----------------------------|-------------|------|
| Supply Voltage Range        | 2.5 to 5.5  | V    |
| Operation Temperature Range | -40 to +85  | °C   |
| Junction Temperature Range  | -40 to +125 | °C   |

## **Thermal Information**

| Parameter                                | Package | Symbol        | Max | Unit |
|--|---------|---------------|-----|------|
| Thermal Resistance (Junction to Ambient) | SOP-16  | $\theta_{JA}$ | 110 | °C/W |
| Thermal Resistance (Junction to Case)    | SOP-16  | θις           | 23  | C/VV |



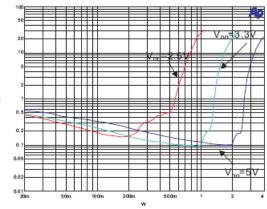
## **Electrical Characteristics** (@ $T_A$ = +25°C, $V_{DD}$ = 5V, Gain = 24dB, $R_L$ = 8 $\Omega$ , unless otherwise specified.)

| Symbol              | Parameter                      | Test Conditions  |                        | Min | Тур  | Max      | Units  |  |
|---------------------|--------------------------------|--|------------------------|-----|------|----------|--|--|
| $V_{DD}$            | Supply Voltage                 |  |                        | 2.5 |      | 5.5      | V  |  |
|                     |                                |  | V <sub>DD</sub> = 5.0V |     | 3.2  |          | W  |  |
|                     |                                | THD+N = 10%, f = 1KHz, $R_L$ = 4Ω                      | V <sub>DD</sub> = 3.6V |     | 1.6  |          |  |  |
|                     |                                |  | V <sub>DD</sub> = 3.2V |     | 1.3  |          |  |  |
|                     |                                | THD+N = 1%, f = 1KHz, $R_L = 4\Omega$                  | V <sub>DD</sub> = 5.0V |     | 2.5  |          |  |  |
|                     |                                |  | V <sub>DD</sub> = 3.6V |     | 1.3  |          | W  |  |
| Б                   | Output Davies                  |  | V <sub>DD</sub> = 3.2V |     | 0.85 |          |  |  |
| Po                  | Output Power                   |  | V <sub>DD</sub> = 5.0V |     | 1.8  |          | w  |  |
|                     |                                | THD+N = 10%, f = 1KHz, $R_L = 8\Omega$                 | V <sub>DD</sub> = 3.6V |     | 0.9  |          |  |  |
|                     |                                |  | V <sub>DD</sub> = 3.2V |     | 0.6  |          |  |  |
|                     |                                |  | V <sub>DD</sub> = 5.0V |     | 1.4  |          | W  |  |
|                     |                                | THD+N = 1%, f = 1KHz, $R_L = 8\Omega$                  | V <sub>DD</sub> = 3.6V |     | 0.72 |          |  |  |
|                     |                                |  | V <sub>DD</sub> = 3.2V |     | 0.45 |          |  |  |
|                     |                                | $V_{DD} = 5.0V, P_O = 1W, R_L = 8\Omega$               | 6 4111                 |     | 0.15 |          | 0.1  |  |
| TUD . N             | Total Harmonic Distortion Plus | $V_{DD} = 3.6V, P_O = 0.1W, R_L = 8\Omega$             | f = 1kHz               |     | 0.11 |          | %  |  |
| THD+N               | Noise                          | $V_{DD} = 5.0V, P_O = 0.5W, R_L = 4\Omega$             | 6 4111                 |     | 0.15 |          | 0,   |  |
|                     |                                | $V_{DD} = 3.6V, P_O = 0.2W, R_L = 4\Omega$             | f = 1kHz               |     | 0.11 |          | %  |  |
| G <sub>V</sub>      | Closed Loop Gain               | V <sub>DD</sub> = 3V to 5V                             | -                      |     | 24   |          | dB   |  |
| PSRR                | Dawar Cumply Dipple Dejection  | V <sub>DD</sub> = 5.0V, Inputs AC-Grounded             | f = 100Hz              |     | -59  |          | dB   |  |
| PSKK                | Power Supply Ripple Rejection  | with $C_{IN} = 0.47 \mu F$ $f = 1 \text{kHz}$          | f = 1kHz               |     | -58  |          |  |  |
| Cs                  | Crosstalk                      | $V_{DD} = 5.0V$ , $P_{O} = 0.5W$ , $R_{L} = 8\Omega$ , | f = 1kHz               |     | -95  |          | dB   |  |
| OS .                | Orossian                       | G <sub>V</sub> = 20db                                  | 1 - 11112              |     |      |          |  |  |
| SNR                 | Signal-to-Noise Ratio          | $V_{DD} = 5.0V, V_{ORMS} = 1V, G_V = 20db$             | f = 1kHz               |     | 80   |          | dB   |  |
| $V_N$               | Output Noise                   | put Noise V <sub>DD</sub> = 5.0V, Inputs AC-Grounded   | No A-Weighting         |     | 100  |          | μV   |  |
|                     |                                | with $C_{IN} = 0.47 \mu F$                             | A-Weighting            |     | 150  |          |  |  |
| Dyn                 | Dynamic Range                  | V <sub>DD</sub> = 5.0V, THD = 1%                       | f = 1kHz               |     | 90   |          | dB   |  |
| η                   | Efficiency                     | $R_L = 8\Omega$ , THD = 10%                            | f = 1kHz               |     | 87   |          | %  |  |
|                     | -                              | $R_L = 4\Omega$ , THD = 10%                            |                        |     | 83   |          |  |  |
|                     | Quiescent Current              | V <sub>DD</sub> = 5.0V                                 | l                      |     | 16   |          | <b>∤</b> .                                       |  |
| ΙQ                  |                                | V <sub>DD</sub> = 3.6V                                 | No Load                |     | 10   |          | mA   |  |
|                     |                                | V <sub>DD</sub> = 3.0V                                 |                        |     | 8    |          | <del>                                     </del> |  |
| I <sub>MUTE</sub>   | Muting Current                 | V <sub>DD</sub> = 5.0V                                 | $V_{MUTE} = 0.3V$      |     | 3.5  |          | mA   |  |
| I <sub>SD</sub>     | Shutdown Current               | V <sub>DD</sub> = 2.5V to 5.5V                         | V <sub>SD</sub> = 0.3V |     | < 1  |          | μΑ   |  |
| R <sub>DS(ON)</sub> | Static Drain-to-Source         | I <sub>DS</sub> = 500mA, V <sub>GS</sub> = 5V          | PMOS                   |     | 180  |          | mΩ   |  |
|                     | On-State Resistor              | NIVIOS   |                        |     | 140  |          | ld l=  |  |
| f <sub>SW</sub>     | Switching Frequency            | $V_{DD} = 3.0V \text{ to } 5.0V$                       |                        |     | 260  |          | kHz  |  |
| Vos                 | Output Offset Voltage          | V <sub>IN</sub> = 0V, V <sub>DD</sub> = 5.0V           |                        | 4.5 | 10   |          | mV   |  |
| V <sub>IH</sub>     | Enable Input High Voltage      | V <sub>DD</sub> = 5.0V                                 |                        | 1.5 | 1.4  | 0.4      | V  |  |
| V <sub>IL</sub>     | Enable Input Low Voltage       | $V_{DD} = 5.0V$  |                        | 4 - | 0.7  | 0.4      |  |  |
| V <sub>IH</sub>     | MUTE Input High Voltage        | $V_{DD} = 5.0V$  |                        | 1.5 | 1.4  | <u> </u> | V  |  |
| VIL                 | MUTE Input Low Voltage         | V <sub>DD</sub> = 5.0V                                 |                        |     | 0.7  | 0.4      |  |  |
| OTP                 | Over Temperature Protection    | No Load, Junction Temperature                          | V <sub>DD</sub> = 5.0V |     | 140  |          | V  |  |
| OTH                 | Over Temperature Hysterisis    | '  | 55                     |     | 30   |          | V  |  |



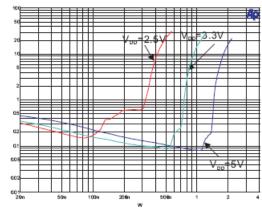
## Typical Performance Characteristics (@TA = +25°C, unless otherwise specified.)

### 1. THD+N vs Output Power



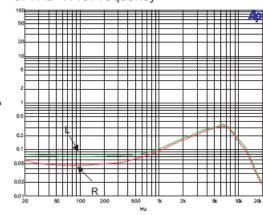
 $R_L=4\Omega$ , Gain = 24dB, f=1kHz

### 2. THD+N vs Output Power



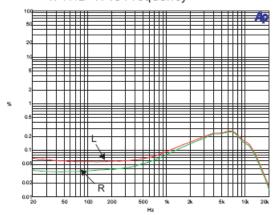
 $R_L=8\Omega$ , Gain = 24dB, f=1kHz

### 3. THD+N vs Frequency



 $V_{DD}$ =5V,  $R_L$ =4 $\Omega$ , Gain = 24dB, Cin=1 $\mu$ F

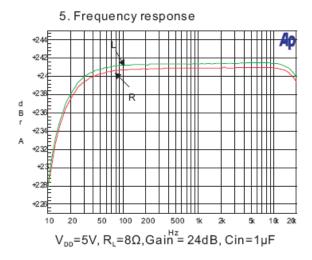
### 4. THD+N vs Frequency

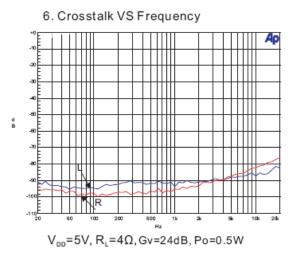


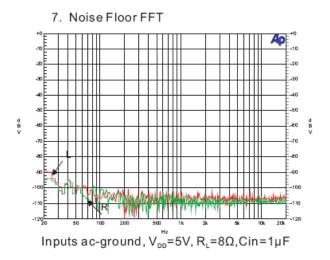
 $V_{DD}=5V$ ,  $R_L=8\Omega$ , Gain=24dB,  $Cin=1\mu F$ 



## Typical Performance Characteristics (cont.) (@TA = +25°C, unless otherwise specified.)







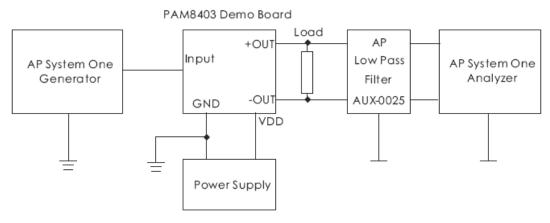


### **Application Information**

#### **Application Note**

- 1. When the PAM8403 works with LC filters, it should be connected with the speaker before it's powered on, otherwise it will be damaged easily.
- 2. When the PAM8403 works without LC filters, it's better to add a ferrite chip bead at the outgoing line of speaker for suppressing the possible electromagnetic interference.
- 3. The recommended operating voltage is 5.5V. When the PAM8403 is powered with four battery cells, it should be noted that the voltage of four new dry or alkaline batteries is over 6.0V, higher than its operation voltage, which will probably damage the device. Therefore, it's recommended to use either four Ni-MH (Nickel Metal Hydride) rechargeable batteries or 3 dry or alkaline batteries.
- 4. One should not make the input signal too large. Large signal can cause the clipping of output signal when increasing the volume. This will damage the device because of big gain of the PAM8403.
- 5. When testing the PAM8403 without LC filters by using resistor instead of speaker as the output load, the test results, e.g. THD or efficiency, will be worse than those of using speaker as load.

#### **Test Setup for Performance Testing**



Notes:

- 1. The AP AUX-0025 low pass filter is necessary for class-D amplifier measurement with AP analyzer.
- 2. Two 22µH inductors are used in series with load resistor to emulate the small speaker for efficiency measurement.

#### **Maximum Gain**

As shown in block diagram (Page 2), the PAM8403 has two internal amplifier stages. The first stage's gain is externally configurable, while the second stage's is internally fixed. The closed-loop gain of the first stage is set by selecting the ratio of  $R_F$  to  $R_I$  while the second stage's gain is fixed at 2x. The output of amplifier 1 serves as the input to amplifier 2, thus the two amplifiers produce signals identical in magnitude, but different in phase by 180°. Consequently, the differential gain for the IC is

 $A_{VD} = 20*log [2*(R_F/R_I)]$ 

The PAM8403 sets maximum RF =142k $\Omega$ , minimum R =18k $\Omega$ , so the maximum closed-gain is 24dB.

### Mute Operation

The MUTE pin is an input for controlling the output state of the PAM8403. A logic low on this pin disables the outputs, and a logic high on this pin enables the outputs. This pin may be used as a quick disable or enable of the outputs without a volume fade. Quiescent current is listed in the electrical characteristic table. The MUTE pin can be left floating due to the internal pull-up.

#### **Shutdown Operation**

In order to reduce power consumption while not in use, the PAM8403 <u>contains</u> shutdown circuitry to turn off the amplifier's bias circuitry. This shutdown feature turns the amplifier off when logic low is <u>applied</u> to the SHDN pin. By switching the SHDN pin connected to GND, the PAM8403 supply current draw will be minimized in idle mode. The SHDN pin can be left floating due to the internal pull-up.



### **Application Information (cont.)**

#### **Power Supply Decoupling**

The PAM8403 is a high performance CMOS audio amplifier that requires adequate power supply decoupling to ensure the output THD and PSRR as low as possible. Power supply decoupling affects low frequency response. Optimum decoupling is achieved by using two capacitors of different types targeting to different types of noise on the power supply leads. For higher frequency transients, spikes, or digital hash on the line, a good low equivalent-seriesresistance (ESR) ceramic capacitor, typically  $1.0\mu\text{F}$ , works best, placing it as close as possible to the device  $V_{DD}$  terminal. For filtering lower frequency noise signals, a large capacitor of  $20\mu\text{F}$  (ceramic) or greater is recommended, placing it near the audio power amplifier.

#### Input Capacitor (C<sub>I</sub>)

Large input capacitors are both expensive and space hungry for portable designs. Clearly, a certain sized capacitor is needed to couple in low frequencies without severe attenuation. But in many cases the speakers used in portable systems, whether internal or external, have little ability to reproduce signals below 100Hz to 150Hz. Thus, using a large input capacitor may not increase actual system performance. In this case, input capacitor  $(C_I)$  and input resistance  $(R_I)$  of the amplifier form a high-pass filter with the corner frequency determined by equation below,

$$f_C = \frac{1}{2\Pi R_1 C_1}$$

In addition to system cost and size, click and pop performance is affected by the size of the input coupling capacitor,  $C_{\rm L}$ . A larger input coupling capacitor requires more charge to reach its quiescent DC voltage (nominally 1/2  $V_{\rm DD}$ ). This charge comes from the internal circuit via the feedback and is apt to create pops upon device enable. Thus, by minimizing the capacitor size based on necessary low frequency response, turn-on pops can be minimized.

#### Analog Reference Bypass Capacitor (CBYP)

The Analog Reference Bypass Capacitor ( $C_{BYP}$ ) is the most critical capacitor and serves several important functions. During start-up or recovery from shutdown mode,  $C_{BYP}$  determines the rate at which the amplifier starts up. The second function is to reduce noise caused by the power supply coupling into the output drive signal. This noise is from the internal analog reference to the amplifier, which appears as degraded PSRR and THD+N.

A ceramic bypass capacitor ( $C_{BYP}$ ) with values of  $0.47\mu F$  to  $1.0\mu F$  is recommended for the best THD and noise performance. Increasing the bypass capacitor reduces clicking and popping noise from power on/off and entering and leaving shutdown.

### **Under Voltage Lock-Out (UVLO)**

The PAM8403 incorporates circuitry designed to detect low supply voltage. When the supply voltage drops to 2.0V or below, the PAM8403 outputs are disabled, and the device comes out of this state and starts to normal function when  $V_{DD} \ge 2.2V$ .

The PAM8403 has short circuit protection circuitry on the outputs to prevent damage to the device when output-to-output or output-to-GND short occurs. When a short circuit is detected on the outputs, the outputs are disabled immediately. If the short was removed, the device activates again.

#### **Over Temperature Protection**

Thermal protection on the PAM8403 prevents the device from damage when the internal die temperature exceeds +140°C. There is a 15 degree tolerance on this trip point from device to device. Once the die temperature exceeds the thermal set point, the device outputs are disabled. This is not a latched fault. The thermal fault is cleared once the temperature of the die is reduced by 30°C. This large hysteresis will prevent motor boating sound well and the device begins normal operation at this point without external system intervention.



## **Application Information (cont.)**

#### How to reduce EMI (Electro Magnetic Interference)

A simple solution is to put an additional capacitor  $1000\mu F$  at power supply terminal for power line coupling if the traces from amplifier to speakers are short (< 20cm).

Most applications require a ferrite bead filter as shown in Figure 2. The ferrite filter reduces EMI of around 1 MHz and higher. When selecting a ferrite bead, choose one with high impedance at high frequencies, and low impedance at low frequencies.

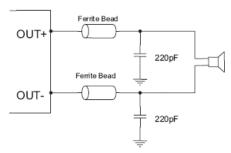
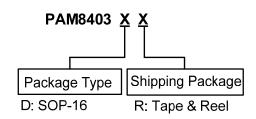


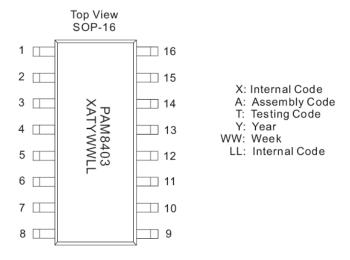
Figure 2: Ferrite Bead Filter to Reduce EMI

## **Ordering Information**



| Part Number | Part Marking        | Package Type | Standard Package     |
|-------------|---------------------|--------------|----------------------|
| PAM8403DR   | PAM8403<br>XATYWWLL | SOP-16       | 2500 Units/Tape&Reel |

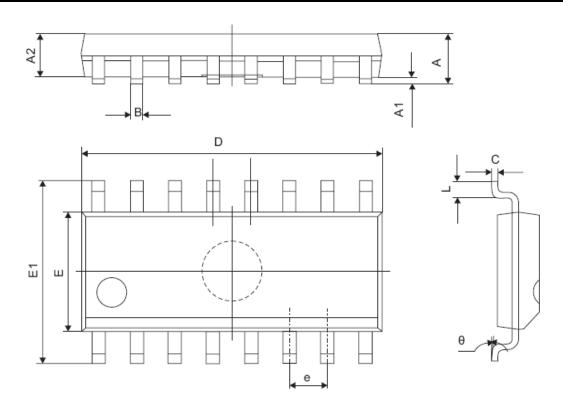
## **Marking Information**





## Package Outline Dimensions (All dimensions in mm.)

### SOP-16



| Symbol | Dimensions Millimeters |        |  |
|--------|------------------------|--------|--|
|        | Min                    | Max    |  |
| А      | 1.350                  | 1.750  |  |
| A1     | 0.100                  | 0.250  |  |
| A2     | 1.350                  | 1.550  |  |
| В      | 0.330                  | 0.510  |  |
| С      | 0.190                  | 0.250  |  |
| D      | 9.800                  | 10.000 |  |
| E      | 3.800                  | 4.000  |  |
| E1     | 5.800                  | 6.300  |  |
| е      | 1.270(TYP)             |        |  |
| L      | 0.400                  | 1.270  |  |
| θ      | 0°                     | 8°     |  |





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